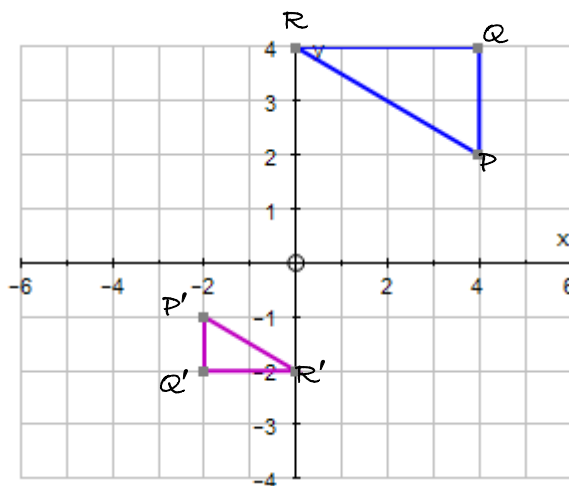


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Section 2: Matrices and transformations

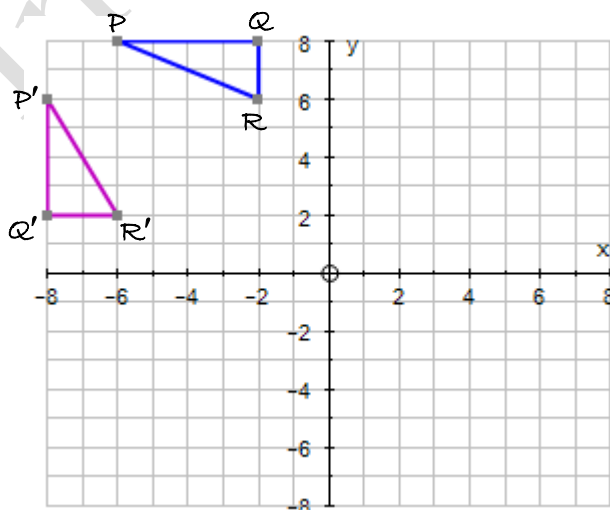
Solutions to Exercise level 2

1. (i) The image of $P(4, 2)$ is $P'(-2, -1)$
 The image of $Q(4, 4)$ is $Q'(-2, -2)$
 The image of $R(0, 4)$ is $R'(0, -2)$



The transformation is an enlargement, scale factor -0.5 , centre the origin.

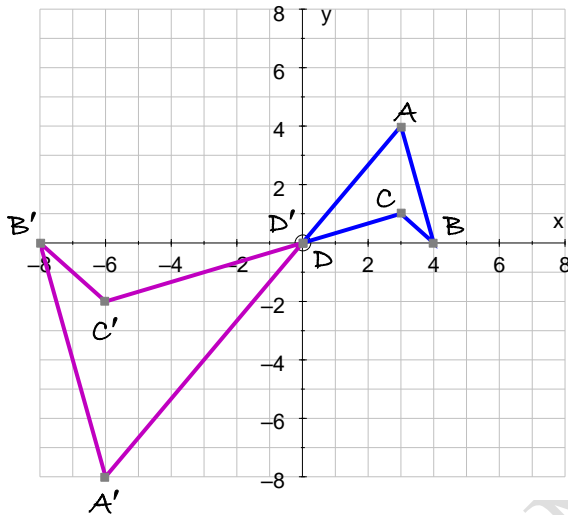
- (ii) The image of $P(-6, 8)$ is $P'(-8, 6)$
 The image of $Q(-2, 8)$ is $Q'(-8, 2)$
 The image of $R(-2, 6)$ is $R'(-6, 2)$



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The transformation is a reflection in the line $y = -x$.

2. The image of the quadrilateral is $A'(-6, -8)$, $B'(-8, 0)$, $C'(-6, -2)$, $D'(0, 0)$.



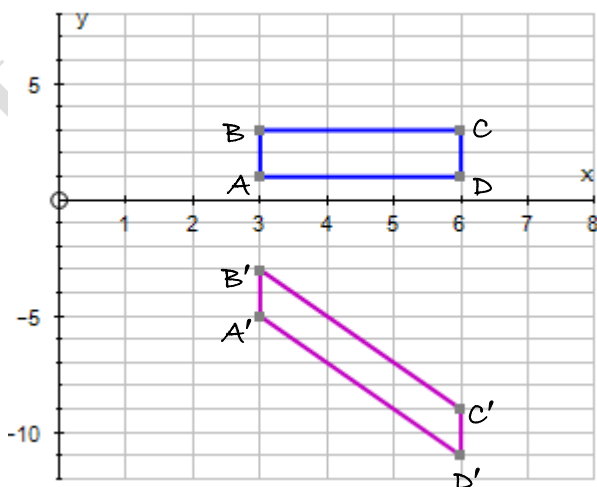
The transformation is an enlargement, scale factor -2 , centre the origin.

The area of the object = $16 - 6 - 2 - 2 = 6$.

The area of the image = $64 - 24 - 8 - 8 = 24$.

The ratio of the image area to the object area is $4 : 1$.

3. The image of $A(3, 1)$ is $A'(3, -5)$
 The image of $B(3, 3)$ is $B'(3, -3)$
 The image of $C(6, 3)$ is $C'(6, -9)$
 The image of $D(6, 1)$ is $D'(6, -11)$.



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The transformation is a shear with the y-axis fixed.

4. The matrix for an anticlockwise rotation through angle θ is

$$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\text{so } R = \begin{pmatrix} \cos 60^\circ & -\sin 60^\circ \\ \sin 60^\circ & \cos 60^\circ \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$$

5. (i) $\begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ (ii) $\begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

6. (i) Comparing $\begin{pmatrix} -\frac{\sqrt{3}}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{\sqrt{3}}{2} \end{pmatrix}$ with $\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$

$$\text{gives } \cos \theta = -\frac{\sqrt{3}}{2} \text{ and } \sin \theta = -\frac{1}{2}$$

Since both are negative, θ must be in the 3rd quadrant

$$\text{so } \theta = 180^\circ + 30^\circ = 210^\circ$$

Rotation through 210° anticlockwise (or 150° clockwise)

(ii) Comparing $\begin{pmatrix} -0.8 & -0.6 \\ 0.6 & -0.8 \end{pmatrix}$ with $\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$

$$\text{gives } \cos \theta = -0.8 \text{ and } \sin \theta = 0.6$$

Since \cos is negative and \sin positive, θ must be in the 2nd quadrant

$$\text{so } \theta = 180^\circ - 36.9^\circ = 143.1^\circ$$

Rotation through 143.1° anticlockwise.

7. Under P , the point $(1, 0)$ is mapped to the point $(-1, 0)$ and the point $(0, 1)$ is unchanged.

$$\text{So } P \text{ is represented by } \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Under Q , the point $(1, 0)$ is mapped to the point $(0, -1)$ and the point $(0, 1)$ is mapped to the point $(1, 0)$.

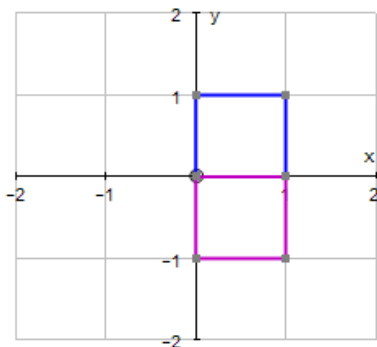
$$\text{So } Q \text{ is represented by } \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}.$$

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The single matrix is $QP = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$.

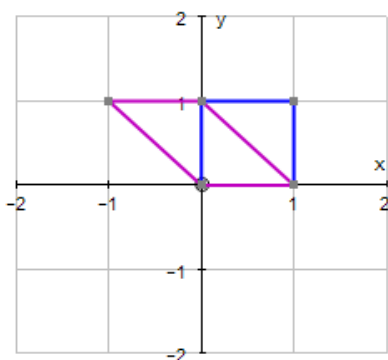
This transformation is a reflection in the line $y = x$.

$$8. \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 1 & 1 \\ 0 & -1 & -1 & 0 \end{pmatrix}$$



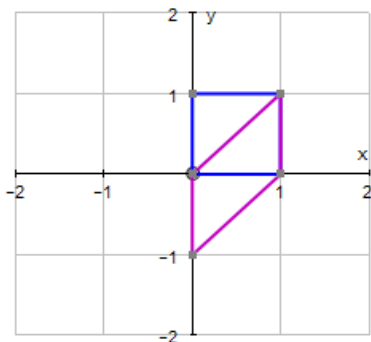
R is a rotation clockwise about the origin through 90° .

$$\begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \end{pmatrix}$$



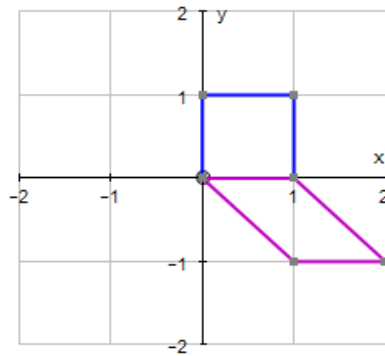
S is a shear parallel to the x -axis.

$$RS = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix}$$

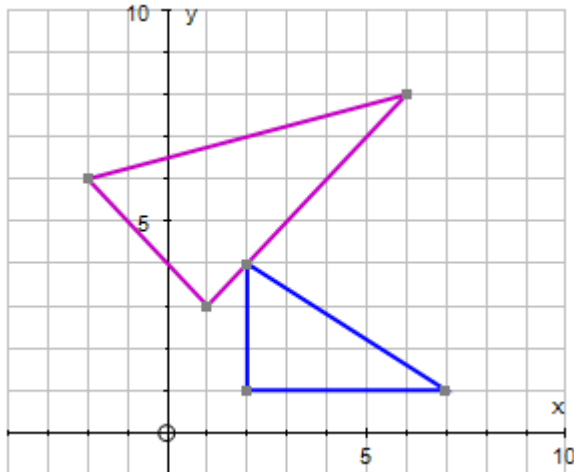


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$$SR = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ -1 & 0 \end{pmatrix}$$



9. (i), (ii) $\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 7 & 2 \\ 1 & 1 & 4 \end{pmatrix} = \begin{pmatrix} 1 & 6 & -2 \\ 3 & 8 & 6 \end{pmatrix}$



(iii) Rotation anticlockwise through θ is represented by $\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$

Enlargement scale factor k is represented by $\begin{pmatrix} k & 0 \\ 0 & k \end{pmatrix}$

Rotation followed by enlargement is represented by

$$\begin{pmatrix} k & 0 \\ 0 & k \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} k \cos \theta & -k \sin \theta \\ k \sin \theta & k \cos \theta \end{pmatrix}$$

Comparing this with $\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$ gives:

$$k \cos \theta = 1$$

$$k \sin \theta = 1 \Rightarrow \tan \theta = 1 \Rightarrow \theta = 45^\circ$$

$$\cos \theta = \frac{1}{\sqrt{2}} \Rightarrow k = \sqrt{2}$$

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The angle of rotation is 45° anticlockwise and the scale factor of the enlargement is $\sqrt{2}$.

$$10. (i) \quad S = \begin{pmatrix} 3 & 0 \\ 0 & 1 \end{pmatrix}$$

(ii) T is a shear with the x -axis fixed, with the point $(0, 1)$ mapped to $(2, 1)$.

$$(iii) \quad M = TS = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 3 & 2 \\ 0 & 1 \end{pmatrix}$$

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